

UNIVERSITÀ DEGLI STUDI DI BRESCIA



A Model for Optimal Crop Selection Based on Conditional Value-at-risk

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IFORS 2014, BARCELONA 13-18 JULY, 2014



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Data and Variable Constraints CSP

CVaR-MILP model

 $ext{CVaR} \\ ext{CSP}(eta)$

Case study Description Results

Conclusions

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- Problem definition
- Expected value approach
 - A first MILP model
- Conditional Value-at-Risk approach
 - A second MILP model
- Discussion of a real case
- Conclusions and future work





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Rural area in Northern Italy



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CVaR CSP(*β*

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- Each crop requires a fixed sequence of operations
 ploughing, seeding, etc.
- Each operation requires a specific tool type
 - ploughing requires a plough
 - working speed and/or operation cost may vary inside the same type and among crops
- Tools are mounted on a tractor machine
 - identical machines
 - limited number available



Problem definition Second part

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- Every operation of every crop has a **time window**
- In a given time slot different operations for different crops can be performed simultaneously, provided that:
 - the required tools and tractors are available
 - the time slot belongs to the appropriate time window
- General task: Optimal selection of crops and optimal assignment over time of their operations so to meet time windows and resource constraints, maximizing the expected profit



Literature review

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Surveys on models to support cropping plan

- Glen, 1987): mathematical models in farm planning
- (Dury et al., 2012): models to support cropping plan and crop rotation

Papers most related to our work

- (Maruyama, 1972): stochastic LP for yield and price uncertainty
- (Danok, McCarl, White, 1980): MILP for machinery selection and crop planning
- (Annets and Audsley, 2002): MOLP for farm planning



EV-MILP model

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- m number of crops
- number of tool types
- A crop *i* is characterized by the ordered sequence of *q_i* operations:

 $j[i, 1], j[i, 2], \ldots, j[i, q_i],$

where j[i, k] is the index of the tool type needed to perform the *k*-th operation of crop *i*

A binary index vector:

 $a_{i,j,k} = \begin{cases} 1, & \text{if } j \text{ is the } k \text{-th operation in crop } i; \\ 0, & \text{otherwise.} \end{cases}$



EV-MILP model Parameters

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- **[** $s_{i,k}, f_{i,k}$] time window for the *k*-th operation of crop *i*
- **[** $[0, T] = [\min_i \{s_{i,1}\}, \max_i \{f_{i,q_i}\}]$ time horizon
- *r*_i expected revenue for one hectare cultivated with crop *i* Obtained from historical data on prices and yields
- *h_{i,k,ℓ}* number of hectares that can be worked out in a time unit performing the *k*-th operation on crop *i*, using the ℓ-th tool of type *j*[*i*, *k*]
- c_{i,k,ℓ} time unit cost of using the ℓ-th tool of type j[i, k] on the k-th operation of crop i
- w number of (identical) tractor machines
- *H* total number of hectares available for cultivation
- u_j number of tools of type j



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I(j, t) subset of crop indices requiring a tool of type j that may be active at time t

 $I(j, t) = \{i : j = j[i, k], t \in [s_{i,k}, f_{i,k}] \text{ for some } k\}$

Binary variables:

	(1,	if compatible machine ℓ is assigned			
$\mathbf{y}_{i,k,\ell,t} = \mathbf{y}_{i,k,\ell,t}$	{	to the k -th operation of crop i at time t ;			
		otherwise.			

Flow variables:

 $z_{i,k,\ell}$ = number of hectares where the *k*-th operation of crop *i* is worked out using tool ℓ



EV-MILP model Constraint 1 and Constraint 2

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Constraint 1: budget constraint on the total area that can be farmed

$$\sum_{i=1}^{m} \sum_{j=1}^{n} a_{i,j,1} \sum_{\ell=1}^{u_j} z_{i,1,\ell} \le H$$

Constraint 2: the hectares worked out by a given crop must be the same for every operation on that crop

$$\sum_{j=1}^{n} a_{i,j,k-1} \sum_{\ell=1}^{u_j} z_{i,k-1,\ell} - \sum_{j=1}^{n} a_{i,j,k} \sum_{\ell=1}^{u_j} z_{i,k,\ell} = 0$$

for all i = 1, ..., m and $k = 2, ..., q_i$

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EV-MILP model Constraint 3 and Constraint 4

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Constraint 3: at any time unit *t* every single tool can be assigned to at most one operation on some crop

$$\sum_{i \in I(j,t)} \sum_{k=1}^{q_i} a_{i,j,k} y_{i,k,\ell,t} \leq 1$$

or all
$$j = 1, ..., n; \ell = 1, ..., u_j; t \in [0, T]$$

Constraint 4: the number of tool-tractor pairs active at any time must not be greater than *w*

$$\sum_{j=1}^{n} \sum_{i \in l(j,t)} \sum_{\ell=1}^{u_j} \sum_{k=1}^{q_i} a_{i,j,k} \, y_{i,k,\ell,t} \leq w$$

for all $t \in [0, T]$



EV-MILP model Constraints 5-6 and 7-8

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Constraints 5 and 6: a necessary and sufficient quantity of resources must be allocated to every operation of every crop

$$\sum_{j=1}^{n} a_{i,j,k} h_{i,j,\ell} \left(\sum_{t=s_{i,k}}^{f_{i,k}} y_{i,k,\ell,t} - 1 \right) \le z_{i,k,\ell} \le \sum_{j=1}^{n} a_{i,j,k} h_{i,j,\ell} \sum_{t=s_{i,k}}^{f_{i,k}} y_{i,k,\ell,t}$$

for all
$$i = 1, ..., m$$
; $k = 1, ..., q_i$; $\ell = 1, ..., u_{j[i,k]}$

Constraint 7 and 8: nonnegativity and binary restriction

 $z_{i,k,\ell} \ge 0$ and $y_{i,k,\ell,t} \in \{0,1\}$

for all i, k, ℓ , and t



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Objective: difference between expected revenues and (certain) costs

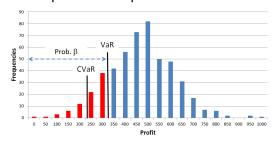
$$\sum_{i=1}^{m} \left(\overline{r}_{i} \sum_{j=1}^{n} a_{i,j,1} \sum_{\ell=1}^{u_{j}} z_{i,1,\ell} - \sum_{k=1}^{q_{i}} \sum_{j=1}^{n} a_{i,j,k} \sum_{\ell=1}^{u_{j}} c_{i,j,\ell} \sum_{t=s_{i,k}}^{t_{i,k}} y_{i,k,\ell,t} \right)$$

- CSP Crop Selection Problem
 - Maximise the above Objective subject to Constraints 1-8



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- In model CSP, profit p(x, r) is a function of our decision
 (x) and uncertain prices (r)
- **Value-at-Risk** (VaR): $Prob\{p \le VaR\} = \beta$ (for a fixed β)
- Conditional Value-at-Risk (CVaR): Conditional expectation of profits lower than VaR



 CVaR is a coherent risk measure with several nice properties (Pflug, 2000)



CVaR-MILP model Maximizing CVaR

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- For a given value of β, we pursue risk minimization through CVaR maximization
- Given *S* scenarios, this can be done (approximately) through the following model (Rockafellar and Uryasev, 2000):

$$\begin{array}{l} \max \, \eta - \frac{1}{\beta} \sum_{s=1}^{S} \pi_{s} d_{s} \\ \text{subject to } \eta - p(\mathbf{x}, \mathbf{r}_{s}) \leq d_{s} \quad (s = 1, \cdots, S) \\ d_{s} \geq 0 \; (s = 1, \cdots, S), \mathbf{x} \in X \end{array}$$

where:

- **r**_s is the s-th possible price realization (scenario);
 π_s is its probability
- X is the set of feasible crop assignments



CVaR-MILP model

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r_{i,s} revenue of crop *i* under scenario *s π_s* = 1/*S* for all scenarios CSP(β):

$$\begin{array}{ll} \max & \eta - \frac{1}{\beta S} \sum_{s=1}^{S} d_{s} \\ \text{subject to} & \eta - \sum_{i=1}^{m} \left(r_{i,s} \sum_{j=1}^{n} a_{i,j,1} \sum_{\ell=1}^{u_{j}} z_{i,1,\ell} \\ & - \sum_{k=1}^{q_{i}} \sum_{j=1}^{n} a_{i,j,k} \sum_{\ell=1}^{u_{j}} c_{i,j,\ell} \sum_{t=s_{i,k}}^{f_{i,k}} y_{i,k,\ell,t} \right) \leq d_{s} \\ & (s = 1, \dots, S) \\ & d_{s} \geq 0 \quad (s = 1, \dots, S) \end{array}$$

+ CSP constraints

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Data

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- H = 100 hectares; m = 4 crops
- w = 4 tractors
- n = 9 ops./tool types; $|u_j| = 2$ for all j
 - Operating costs and working speeds
 - Source: Farmer
- Prices: monthly prices from 2000 to 2009
 - Source: ISMEA
- Yield per hectare: yearly averages from 2000 to 2009
 - Source: www.istat.it
 - Each average yield perturbed 5 times according to a Beta distribution
- A total of 120 × 5 = 600 scenarios



Implementation

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- Models implemented using IBM ILOG CPLEX Optimization Studio 12.5
 - CPLEX solver used the default settings
- Code run on an Intel Core i5 2.70GHz, 4MB RAM processor with 64 bit Windows 7 Pro
- Model size and Computational times
 - **CSP** model: 4092 rows and 809 columns
 - reduced to 349 rows and 618 columns
 - solved to optimality in less than 1 sec. of total time
 - **CSP(** β **)** with β = 0.05, 0.01: 4693 rows and 1410 columns
 - reduced to 950 rows and 1219 columns
 - best integer solution found in the first 10 seconds and then stalling with a gap steadily around 0.10%





0%

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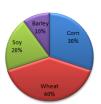
CVaR-MILP model

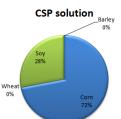
CVaR CSP(β

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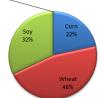
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Farmer's solution

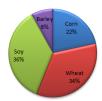




CSP(0.05) solution



CSP(0.01) solution



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Statistics

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Initial budget: 15000 euro

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		CSP		
Statistics	Farmer's sol.	Value	Variation	
Ave. Profit	101 124.87	124 628.50	23%	
Cost	8090.00	13223.50	63%	
Cash surplus	6910.00	1776.50		
Ave. Profit + Cash	108034.87	126405.00	17%	
Max Profit	235 712.82	289 832.27	23%	
Min Profit	48 559.39	37 149.23	-23%	
Variance	1.0449E+09	2.2801E+09	118%	
		CSP(0	.05)	
Statistics		Value	Variation	
Ave. Profit		99 921.02	-1%	
Cost		6154.50	-24%	
Cash surplus		8845.50		
Ave. Profit + Cash		108766.52	1%	
Max Profit		209 998.52	-11%	
Min Profit		56 723.22	17%	
Variance		9.1787E+08	-12%	
		CSP(0	CSP(0.01)	
Statistics		Value	Variation	
Ave. Profit		97 076.49	-4%	
Cost		6513.50	-19%	
Cash surplus		8486.50		
Ave. Profit + Cash		105562.99	-2%	
Max Profit		200 741.08	-15%	
Min Profit		57 649.54	19%	
		8.6929E+08	-17%	



Profit Distributions Frequency

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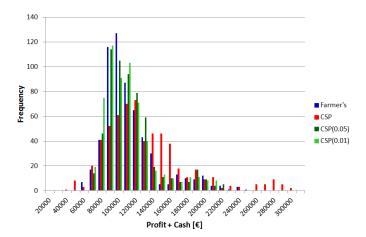
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CSP has a very large range of outcomes

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Profit Distributions Cumulative Frequency (zoom)

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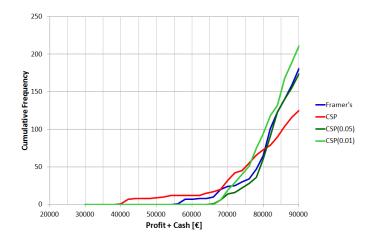
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■ CSP(β) preserves from very bad outcomes

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Gannt Chart

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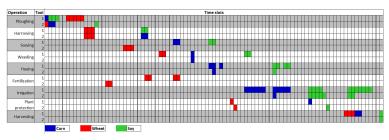
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CSP(0.05) solution (not all time slots displayed):



Resources (tools, tractors) could be better exploited



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Crop mix problem modelled as a CVaR maximization problem with scheduling constraints

- validated on a real case
- more balanced solutions wrt an expected value maximization
- **Extensions** and future work:
 - evaluation of the effects of different resource configurations and the advantages of tool sharing
 - richer models, including decisions about the resources and their cost
 - deeper computational study